



Validation of Clyde River SuperDARN radar velocity measurements with the RISR-C incoherent scatter radar

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Abstract

The study considers simultaneous plasma velocity measurements in the eastward direction carried
10 out by the Clyde River SuperDARN HF radar and Resolute Bay incoherent scatter radar RISR-C.
The HF velocities are found to be in reasonable agreement with RISR velocities up to magnitudes
of 700-800 m/s while for faster flows, the HF velocity magnitudes are noticeably smaller. The
plasma flows eastward component inferred from SuperDARN convection maps (constructed for
the area of joint measurements) shows the effect of smaller HF velocities even at smaller velocities.
15 We show that the differences between the instruments can be significant and prolonged for
observations of strongly-sheared plasma flows.

1 Introduction

20 The Super Dual Auroral Radar Network (SuperDARN) HF radars have been installed to
continuously monitor the $\mathbf{E} \times \mathbf{B}$ plasma drift in the Earth's ionosphere (Greenwald et al., 1995).
To achieve this goal, the radars measure Doppler velocity of ionospheric echoes coming from the
F region. The return signal, in this case, is coherent backscatter from decameter irregularities that
move with the velocity close to the plasma $\mathbf{E} \times \mathbf{B}$ drift. A number of comparisons of SuperDARN
25 velocity measurements with concurrently operating incoherent scatter radars (ISR) that measure
the plasma $\mathbf{E} \times \mathbf{B}$ drift has been performed in the past (Ruohoniemi et al., 1987; Davis et al., 1999;
Milan et al., 1999; Xu et al., 2001; Gillies et al., 2009; Gillies et al., 2010; Bahcivan et al., 2013;
Koustov et al., 2016; Gillies et al., 2018). These observations, overall, supported the above major



assumption of the SuperDARN principle in plasma flow measurements. However, occasional
30 significant differences between HF radar line-of-sight (LOS) velocity and $\mathbf{E} \times \mathbf{B}$ drift component
along the beam have been noticed. Initially, these were thought to originate from differences in the
echo collecting areas (Davies et al., 1999) but the body of the data, published so far, questions this
notion. It is accepted now that the HF velocities are generally smaller (Gillies et al., 2018). One
identified effect leading to this result is the fact the SuperDARN measurements are done under an
35 assumption that the medium has the index of refraction of unity. However, this explanation cannot
account for large differences of more than 20-30%. Koustov et al. (2016) stressed the original
finding by Xu et al. (2001) that the HF velocity magnitudes substantially smaller (up to a factor of
2) than the $\mathbf{E} \times \mathbf{B}$ drift component for high-speed flows of >1000 m/s. Furthermore, often the HF
velocity magnitudes are above the $\mathbf{E} \times \mathbf{B}$ component (e.g. Ruohoniemi et al., 1987; Koustov et al.,
40 2016; Gillies et al., 2018). Such observations have been interpreted in terms of lateral deviation of
HF radar beams (Koustov et al., 2016; Gillies et al., 2018). Some SuperDARN-ISR velocity
inconsistencies have been associated with the occurrence of E region echoes at traditionally
expected F region ranges for SuperDARN (Bahcivan et al., 2013; Gillies et al., 2018).

Despite an obvious progress, HF-based $\mathbf{E} \times \mathbf{B}$ measurements require further investigation
45 if one wants to further improve the quality of the convection mapping with HF radars. In addition,
although all SuperDARN radars work on the same principle and often even have identical
hardware, validation work for every unit is highly desirable to be confident in reliability and
consistency of measurements across the network.

In this study, we undertake a validation work for the Clyde River (CLY) SuperDARN
50 radar. In a broader context, this effort is a complementary one to the previous validation work for
the Rankin Inlet (RKN) and Inuvik (INV) SuperDARN radars by Koustov et al. (2009), Mori et
al. (2012), Bahcivan et al. (2013), Koustov et al. (2016) and Gillies et al. (2018). Since currently
the CLY radar contributes significantly to the global-scale convection mapping with SuperDARN
such work is of particular importance. We take here an advantage of the availability of the $\mathbf{E} \times \mathbf{B}$
55 drift measurements with recently installed incoherent scatter radar RISR-C (Canada) at Resolute
Bay (RB), e.g. Gillies et al. (2016). An important aspect of the present work is that we compare
CLY and ISR-based velocities in a different way as compared to the previous studies.

Traditionally, gate-by-gate comparison of data from two radar systems making
measurements in roughly the same directions is performed, e.g. Gillies et al. (2018). Such an



60 approach cannot be implemented for the CLY/RISR-C geometry because none of these radars'
beams are close enough (see map on Fig. 1 in Gillies et al. (2018)). For this reason, we consider
RISR-C two-dimensional vectors in a certain area (which are inferred by merging data from
multiple individual beams using the approach by Heinselman and Nicolls (2008)) and compare
them with highly-averaged CLY data (over 3 beams and 4 gates). Thus, we assess the data in a
65 statistical sense, in terms of the average (median) velocities over a large space domain.

To further substantiate our reasoning, we remind the reader that SuperDARN global-scale
maps of plasma flow obtained with the Potential Fit technique (Ruohoniemi and Baker, 1998;
Shepherd and Ruohoniemi, 2000) are built using median-filtered LOS velocities, the so-called
gridded velocities. These are inferred from up to 27 raw velocity LOS values (if available) in
70 certain beam/gate and in \pm one range gate for \pm one radar beam and for \pm one radar scan. This
implies that what eventually goes into the Potential Fit procedure is a highly smoothed HF velocity
covering 3-6 min of raw data and a significant space domain. In this view, there is a sense in
considering 2-D RISR-C data and compare them with HF velocity medians, or vectors from the
convection maps, over large spatial areas of overlap.

75 Although our aim is to validate the CLY velocity measurements, there is additional value
for the CLY-RISR comparison. The RISR method of velocity vectors estimations has some
limitations as well (Heinselman and Nicolls, 2008) and the technique employed needs testing by
itself. A couple of the limitations are a lack of velocity measurements along magnetic field lines
and the expectation of spatially quasi-uniformity of flows, which is not always satisfied. Thus, our
80 work can be considered as a mutual validation of both radar system performance. Compatibility
of the vector estimates by RISR and SuperDARN is highly expected, but to what degree has not
been reported so far.

2 Geometry of RISR-C and Clyde River radar observations

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Figure 1 shows the fields of view (FOV) of the CLY and RKN SuperDARN radars starting from
range gate 5 and the location of the RB incoherent scatter radar RISR-C, which we will simply
refer to as the RISR radar starting from here. This radar makes measurements in multiple beams;
it uses 11 beams in the so-called “world-day” mode and 51 beams in the so-called “imaging” mode.
90 Measured line-of-sight velocities in all the beams and at all ranges are used to infer 2-D vectors of



the $\mathbf{E} \times \mathbf{B}$ flow according to the procedure outlined by Heinselman and Nicolls (2008). The resultant vectors are reported with 0.25° step of magnetic/geographic latitude. The points where the measurements are assigned are roughly shown in Fig. 1 (for the height of 300 km). The actual center line for the points of data merging depends on data availability in specific beams (Gillies et al., 2018).

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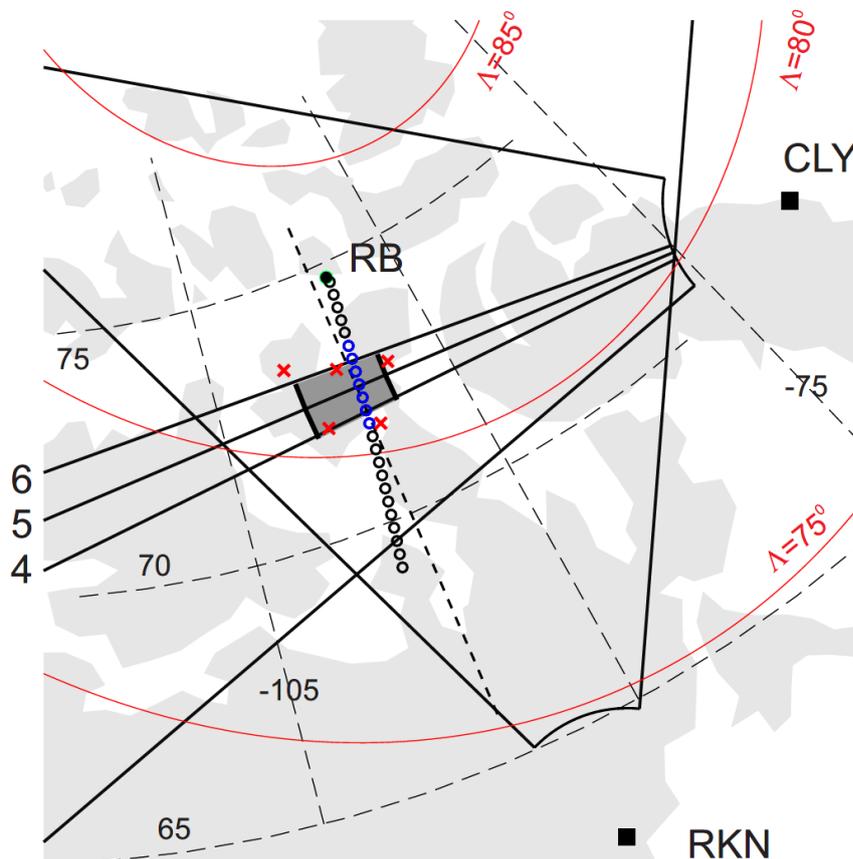


Figure 1: Field of view of the SuperDARN radar at RKN and CLY. The black straight lines are the orientation of specific beams (4-6 for CLY) whose data were investigated. Shaded areas represent areas of HF radar data averaging. RB is the location of the RISR-C incoherent scatter radar. The radar reports $\mathbf{E} \times \mathbf{B}$ vector with a step of 0.25° of geographic latitude for points shown as black circles stretching roughly along the magnetic meridian crossing the RB zenith. The blue-colored circles are those locations whose data were used for comparison with the CLY measurements. The solid red lines are the magnetic latitudes of 75° , 80° and 85° .

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Figure 1 also shows the orientation of the CLY beams 4, 5, 6 (their centers) and the area where data were considered, the shaded rectangle outlined by beams 4 and 6 between range gates



18-22. The monitored ionospheric region is centered at geographic latitude of $\sim 72.5^\circ$. An important feature of this area is that here the CLY beams 4-6 are almost parallel to the lines of equal geographic latitude at the chosen radar range gates, as seen in Fig. 1. This means that one
110 can directly compare CLY LOS velocity and the Eastward component (in geographic coordinates, as given by RISR) of a RISR $\mathbf{E} \times \mathbf{B}$ velocity vector. We note that the area of CLY observations was also covered by measurements from the RKN and INV radars so that SuperDARN convection maps were usually well constrained.

115 **3 Methodology of the LOS velocity comparison**

We consider here an extensive data set comprising of RISR observations over the entire year 2016. Overall, about 1,000 hours of RISR measurements were available. The radar typically worked for
120 24 hours switching, once-in-a-while, its mode of operation, except the world-day mode which usually covered an entire day. The range resolution of measurements in both modes is ~ 50 km. The data are available for two seasons, winter and equinoxes, with no measurements for summer time. We consider here 5-min RISR data because they have much smaller errors in measurements than 1-min data that are available as well.

Figure 2 shows the total number of 5-min intervals of joint RISR-CLY radar measurements
125 for various UT. The number of the intervals was much larger during noon-dusk time (local solar noon is at about 19:00 UT). This is because of preferential occurrence of CLY echoes at ranges of interest during daytime (Ghezelbash et al., 2014). Unfortunately, not all available periods are suitable for the comparison. This is because the CLY data are often contaminated by ground scatter that profoundly affects the comparison, as shown recently by Gillies et al. (2018). Such periods
130 have been dropped from further consideration.

Our approach to the CLY-RISR velocity comparison is as follows. We first select 5-min
135 period of RISR velocity measurements at latitudes of $\sim 71.625^\circ - 73.125^\circ$, see blue circles in Fig. 1, and compute median velocity value for RISR. We then consider median values of the CLY velocity over matched 5-min intervals in 3 beams and 4 gates, mentioned above. The matched data are then entered into a common dataset.

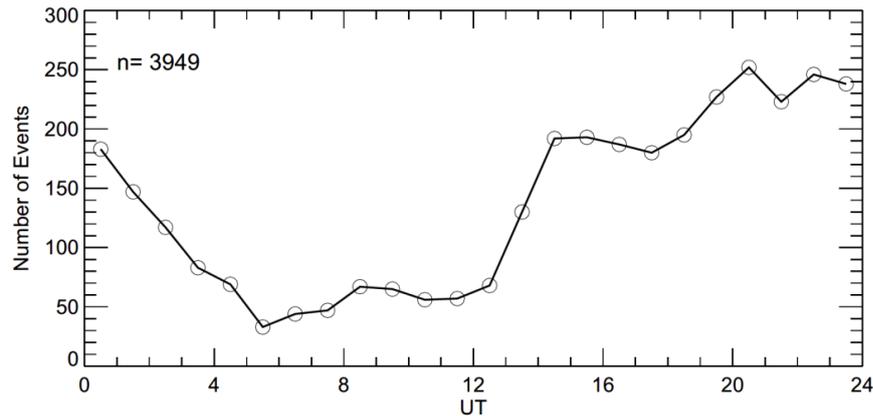


Figure 2: Number of CLY/RISR 5-min intervals of joint observations for all events considered. Total number of available intervals is shown in the top-left corner.

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4 Results for CLY LOS velocity - RISR comparison

Figure 3a shows the CLY LOS velocity versus the RISR Eastward $\mathbf{E} \times \mathbf{B}$ component for the entire
145 dataset, produced as described above. The total number of points is close to 4000, which is a
significant number. Overall, both positive and negative velocities are well represented. Although
some spread in data is present, a significant amount of points is located close to the bisector of
perfect agreement. To assess the plot, we binned the data according to RISR measurements by
using 100-m/s bins. Binned in this way data are shown by black-white dots. The vertical black bars
150 crossing each dot are the binned CLY velocity value \pm one standard deviation. We also binned the
data of Fig. 3 according to bins of the CLY velocity, pink asterisks (shown by thin symbols in
order not to contaminate the plot).

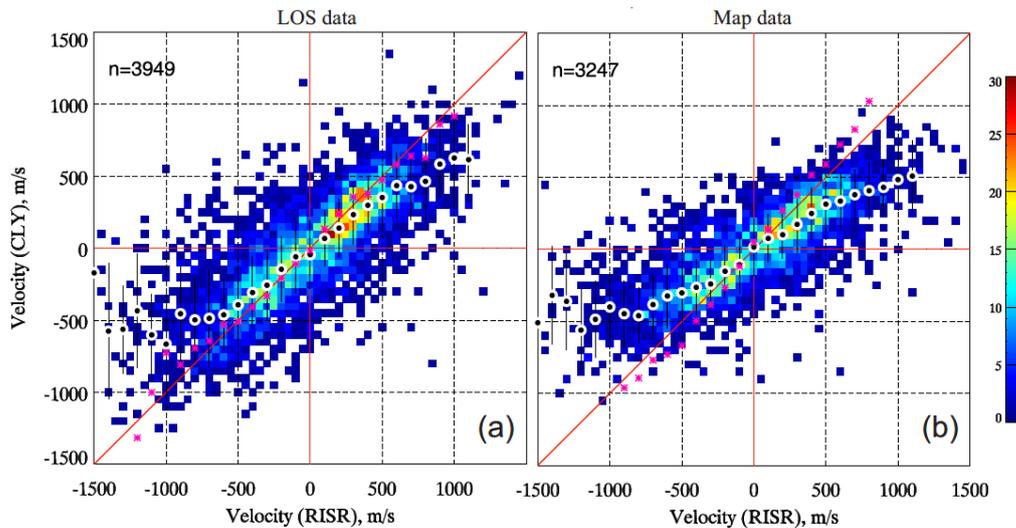


Figure 3: (a) Scatterplot of the CLY LOS velocity versus $\mathbf{E} \times \mathbf{B}$ eastward velocity component as inferred by RISR. Total number of points n is shown in the top left corner. The black-white dots are medians of the CLY velocity in 100-m/s bins of RISR velocity. The black vertical lines are the standard deviations of the CLY velocity in each bin. The pink dots are medians of the RISR velocity in 100-m/s bins of CLY measurements (b) The same as (a) but the flow eastward component inferred from SuperDARN flow maps was considered.

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The black-white dots are reasonably close to the line of the perfect agreement. The pink asterisks are actually very close to the bisector line. Good alignment with the bisector and not very strong differences between the location of the black dots and pink asterisks indicate that the velocities are related almost linearly, especially in the range from -500 m/s to +500 m/s. One clear departure of the back dots from the bisector is at large RISR velocity magnitudes of > 750 m/s. If one to describe the dependence by a linear fit line between velocities of ± 1000 m/s, the slope of the fit line is ~ 0.65 .

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5 Methodology of “vector” comparison between SuperDARN and RISR

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The approach to the velocity vector comparison between the RISR and SuperDARN data is as follows. We restrict the consideration to the same area of joint CLY-RISR observations as in the LOS comparison, Fig. 1. Here the SuperDARN convection vectors are available at geomagnetic latitudes of $80.5^\circ - 81.5^\circ$ and $\sim 7^\circ$ of magnetic longitude. We selected 3 closest (to the area of CLY LOS velocity assessment) grid nodes locations at MLAT= 81.5° and 2 closest grid nodes

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located at $MLAT=80.5^\circ$, as indicated in Fig. 1 by red crosses. For each vector location, an eastward component of the flow was computed and the median value (out of potentially 5 values, although for some periods it was as low as 1 measurement) was selected as a representative value of the eastward plasma flow component according to a specific SuperDARN map. In terms of time, because RISR measurements considered had ~ 5 -min resolution, standard SuperDARN convection maps with 5-min integration time were produced. This is not a traditional temporal resolution for the SuperDARN mapping (which is 2 min); such data processing has been done to avoid the need of additional averaging of 2-min SuperDARN maps. Unfortunately, the beginnings of RISR measurement intervals were often at irregular time while SuperDARN maps were produced over exact time slots such as 0-5 min, 10-15 min and so on. For comparison, only data from the two systems that were less than 2 min apart were considered. For this reason, even when both radar systems were operational, the actual number of joint points per hour was below the expected number of 12.

For RISR, the eastward $\mathbf{E} \times \mathbf{B}$ velocity component has been usually available in all points shown by open circles in Fig. 1. For the comparison with SuperDARN vectors, only measurements at geographic latitudes between $71.625^\circ - 73.125^\circ$ (given with a step of 0.25° , blue-colored circles in Fig. 1) were considered, and the median value of the eastward component was computed. Obtained data pairs were entered into a common dataset for all the events available. We ended up with a slightly shorter data set than that for the LOS velocity comparison. We stress that although the data for the comparison were along one specific direction, geographic east, two-dimensional vectors were used in determination of the velocity component for both systems.

6 Results for “vector” comparison between SuperDARN and RISR

Figure 3b plots eastward component of the plasma flow according to the two systems. The data spread looks similar to that of Fig. 3a (the LOS comparison). We assessed the plot of Fig. 3b by binning the data similarly to Fig. 3a, see open circles. Overall agreement of the data clearly holds.

Several details of the data of Fig. 3b are consistent with the data of Fig. 3a. First, the SuperDARN map-based velocities are somewhat smaller than those of RISR. This is recognizable through an obvious deviation of the distribution maxima from the bisector of ideal agreement, especially at RISR positive velocities of > 500 m/s. If one to describe the dependence by a linear



fit line to the velocity medians in bins (open circles) between ± 1000 m/s, the slope of the fit line is 0.54. Secondly, the tendency of having smaller SuperDARN velocity is progressively stronger at larger RISR magnitudes. This feature is seen for both positive and negative RISR velocities.
210 Finally, consistent with previous reports (Koustov et al., 2016; Gillies et al., 2018), there is a number of points for which the radars show opposite velocity polarity; This was more frequent for small RISR velocities. Although the plot of Fig. 3 shows good consistency of the data provided by the two radar systems; the differences can be as large as a factor of 2 in individual measurements.

The agreement between the convection vectors given by RISR and SuperDARN is highly
215 expected. We see that the consistency deteriorates once 2-D data are involved, but mostly at intermediate velocity magnitudes of 300-600 m/s with the SuperDARN velocities being slower. Interestingly, the differences for large velocity magnitudes in Fig. 3b are comparable to those in Fig. 3a. We think that the deterioration of the agreement at intermediate velocity magnitudes is due to the broader area of SuperDARN data averaging for the 2-D comparison. In this case, there
220 are more chances for SuperDARN to involve ground-scatter contaminated measurements giving effectively slower grid velocities to the fitting procedure.

7. On possible reasons for velocity disagreements

225 One popular opinion about SuperDARN velocity measurements is the systematic “underestimation” of the velocity by the radars due to the assumption for the index of refraction to be one in HF measurements (starting from Gillies et al., 2009 and Ponomarenko et al., 2009). We attempted to evaluate the importance of this effect on our data set. A plot similar to that of Fig. 3a was produced, but with the CLY velocity being corrected by considering the electron density
230 (at the F region peak) measured by RISR. The plot looked very much similar to that of Fig. 3a. We assessed the plot by applying the linear fit line to the HF velocity medians in 100-m/s bins of RISR velocity, considering the range of almost linear dependence, between -1000 and +1000 m/s of RISR velocities. The slope of the best fit line improved to ~ 0.75 (from ~ 0.65). This improvement is consistent with the previous studies except the slope is not quite close to 1. We also investigated
235 the diurnal variation of the velocity ratio $R = \frac{Vel_{HF}}{Vel_{RISR}}$. Gillies et al. (2018) plotted R against UT time considering the RKN SuperDARN radar. The idea is that the HF velocity decrease due to



the index of refraction effect should be strongest whenever the electron density in the scattering volume is highest. For the winter/equinoctial ionosphere over Resolute Bay, the largest densities are systematically observed at near local solar noon and afternoon hours (18-22 UT) (e.g. Ghezlbash et al., 2014; Themens et al., 2017). It is therefore expected that the velocity ratio R would be smallest at near noon/afternoon hours, and this is what has been reported by Gillies et al. (2018) for the RKN radar. The nighttime results by Gillies et al. (2018) are more confusing. First, strangely, the ratios here were often above 1 at latitudes southward of RB and systematically below 1 (but not as strong as at near noon hours) at latitudes poleward of RB. Gillies et al. (2018) indicated that the vertical plasma flow velocities in RISR measurements were, very likely, estimated not correctly for nighttime observations. Since the observation area in our comparison is close to RB, we can expect that this effect can also affect the RISR-CLY comparison.

Figure 4 plots the hourly-median ratio R as a function of time for our CLY-RISR data set. One can see that R varies significantly. It is decreased during daytime (noon is at about 19:00 UT) as compared to that of dawn/prenoon hours (12-18 UT), but the values are smallest during nighttime (midnight is at about 07 UT). Interestingly, the average ratio over all UTs is 0.83, which is closer to 1 than the slopes of the lines in Figs. 3. This is probably because infrequent high-velocity data are averaged out by dominating data at low velocities in certain bins of Fig. 4.

We think that the low nighttime R values are resulted from “overestimation” of true plasma drift in a plane perpendicular to the magnetic field by RISR in the midnight sector. We note that this is not quite consistent with Gillies et al. (2018) who interpreted their nighttime data in terms of effectively decreased RISR LOS velocities while our data suggest effectively increased RISR velocity magnitudes.

Gillies et al. (2018) believe that large nighttime ratios of RKN to RISR velocity could be due to errors in HF measurements because the RKN beams can experience significant lateral deviations. This explanation cannot be applied to our observations. This is because the CLY radar observes azimuthally, along the average plasma flow most of the time (except of short periods at near noon and near midnight when the flows are predominantly meridional) so that lateral deviations of the CLY beams would give both smaller and larger velocity magnitudes.

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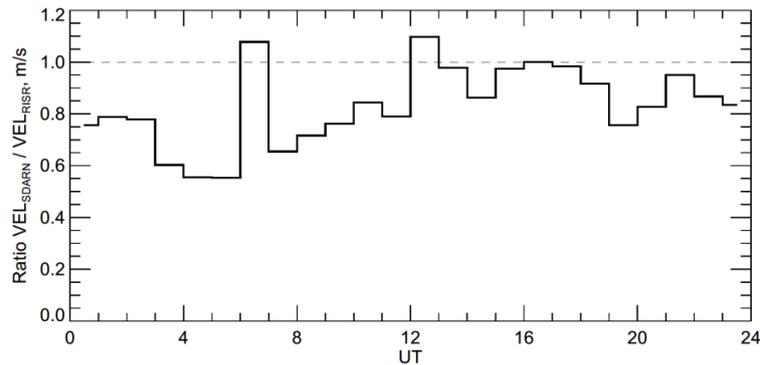


Figure 4: Line plot of the hourly median velocity ratio R versus UT for the CLY radar. The data set is the same as for Fig. 3a.

270 We think that the HF-RISR velocity inconsistency can also originate, at least partially,
from the nature of HF signal formation. The effect has been discussed in general terms by
Uspensky et al. (1989) as applied to E region coherent scatter and by Koustov et al. (2016) for F
region coherent backscatter. The flows in the nighttime ionosphere are very likely to be more
275 patchy/grainy with occasional occurrence of regions with enhanced flow magnitude (low electron
density) and decreased flow magnitude (high electron density). We argue that in a case of the
patchy ionosphere, there is a good chance that the ratio R would be smaller as compared to the
case of uniform ionosphere and homogeneous flow. Flow enhancements/decreases affect both
RISR and HF measurements but in a profoundly different manner. RISR radar would average the
280 velocity in patches with enhanced and depleted electron density equally, and it would report what
can be classified as the “background” flow velocity. In the presence of electron density patches
with enhanced and decreased $\mathbf{E} \times \mathbf{B}$ flows, HF radars would preferentially detect stronger signals
from those areas where the electron density is enhanced, and the electric field (flow magnitude) is
decreased so that it would show somewhat smaller velocity than the background value measured
by an incoherent scatter radar.

285 It is conceivable to have an opposite situation with HF velocities above the background
flow if regions with enhanced density have stronger local electric field, as discussed in Uspensky
et al. (1989). In this respect, Koustov et al. (2016) and Gillies et al. (2018) noticed that HF
velocities could be larger than the $\mathbf{E} \times \mathbf{B}$ drift component measured by ISRs. Occasional such
points are seen in previously published data, for example in Ruohoniemi et al. (1987) and Davies
290 et al. (1999). Our data of Fig. 3 also show such points but, overall, the data agree. Although both



Koustov et al. (2016) and Gillies et al. (2018) related the effect to lateral deviations of the HF radar beams from the expected directions, it partially could be due to the above effect of ionospheric microstructuring.

Potentially, low R values can be related to the occurrence of misidentified ionospheric scatter because some ionospheric echoes with low velocities can actually be ground or mixed scatter. Gillies et al. (2018) showed that removal of points that could potentially be affected by ground scatter improves the RKN-RISR velocity agreement significantly. Our analysis showed that ground scatter is rare during winter/equinox nighttime for the CLY radar which is consistent with low nighttime F region densities (Ghezelbash et al., 2014; Themens et al., 2017). We also have to remind that obvious periods with CLY ground scatter contamination have been removed from our consideration in Fig. 3.

Investigating our database, we identified one special situation when the RISR-SuperDARN velocity disagreements were particularly strong. Figure 5 gives an example of CLY-RISR observations on 4 March 2016 where RISR and CLY velocities differ consistently by several hundred m/s over a period of almost 2 hours.

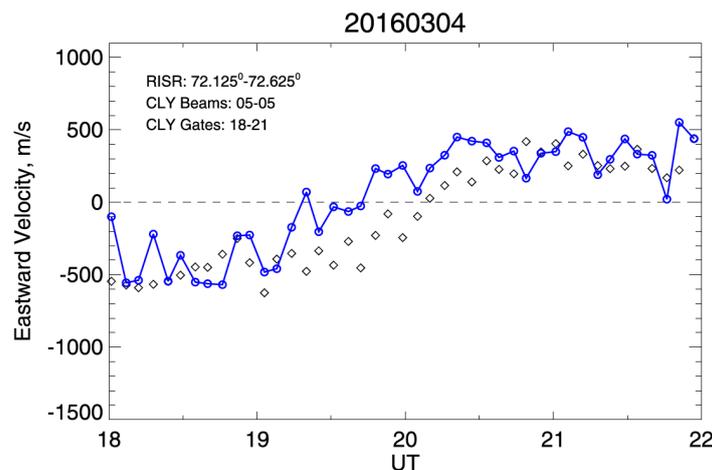


Figure 5: Eastward component of the $\mathbf{E} \times \mathbf{B}$ drift as measured by RISR (red diamonds, 5-min resolution data) and matched velocity medians of CLY observations (5-min medians of original 1-min measurements in beams/gates “overlapping” the region of RISR observations) for the event of 04 March 2016.



Figure 6a illustrates, just for one CLY velocity scan, the typical spatial velocity distribution
 315 within the radar FoV, for the above event. A sharp change in the LOS velocity polarity from
 positive values in low number beams to negative values in high number beams is noticeable. The
 polarity transition occurs in the central beams 5-7. Figure 6b gives a global-scale map of plasma
 flow inferred from all SuperDARN radar measurements. The map has a number of vectors
 originated from the RKN and INV radar measurements on a top of those from CLY measurements.
 320 Presence of highly-curved flows is evident at near noon hours. Under these conditions, both
 SuperDARN and RISR can have difficulties in the construction of a 2-D vector field.

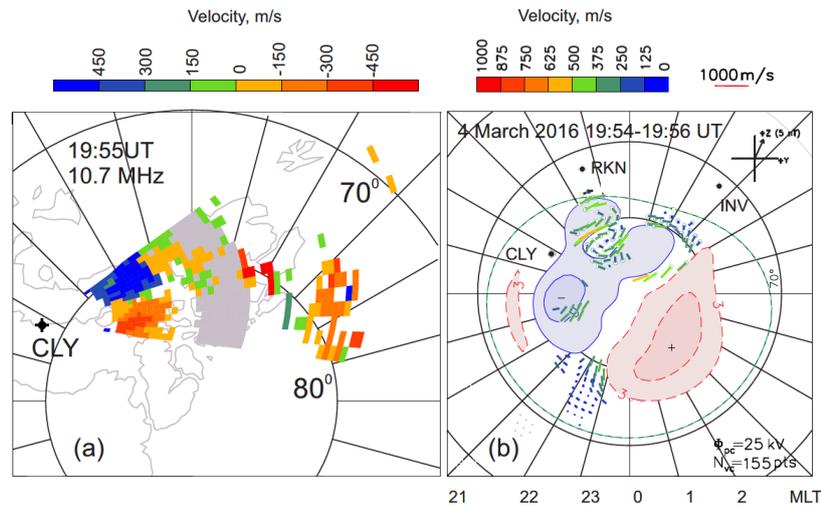


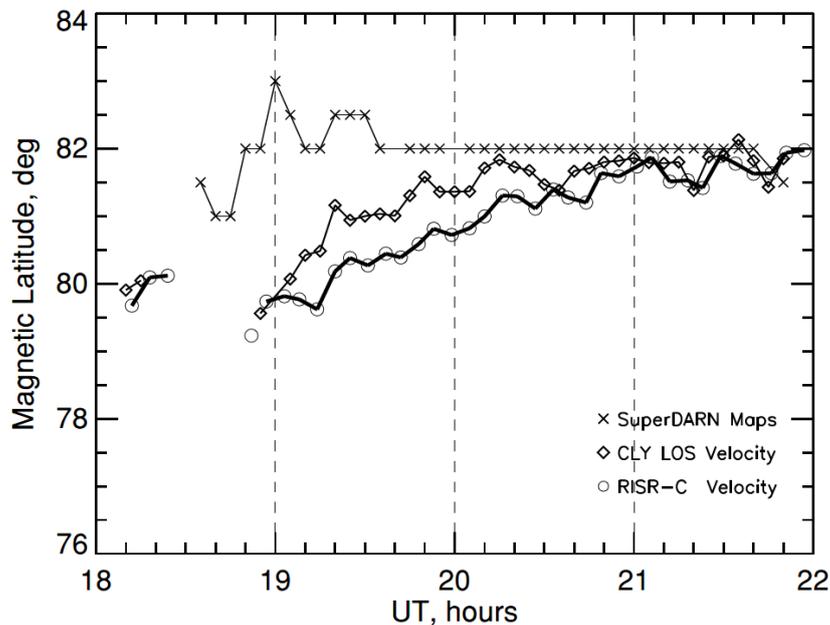
Figure 6: (a) A CLY LOS velocity map at 19:55 UT on 04 March 2016 and (b) a standard 2-min
 325 convection maps inferred from all SuperDARN radar measurements for the same period of time.

We comment that the flows seen in Fig. 6 are sunward, roughly along the magnetic
 meridian at near noon hours, signifying the occurrence of a reverse convection cell. This is highly
 expected since the IMF B_z was steady at about +5 nT starting from 18:30 UT all the way until ~22
 UT for this event.

330 Evaluation of the extent the SuperDARN and RISR vectors are affected by the shear in the
 flow is difficult. We realized visually that the centers (foci) of the convection cells, according to
 RISR and SuperDARN, do not coincide in latitude for many cases in this event. In addition, we
 realized that, while selecting the SuperDARN map data at lower latitudes, the agreement between
 the RISR and SuperDARN map data improves dramatically.



335 To investigate further, we determined the location of the convection reversal boundary
(CRB) for the reverse convection cell (like that shown in Fig. 6b) by considering the standard 2-
min SuperDARN maps, CLY velocity-scan maps and by looking at the reversal in the latitudinal
profile of the RISR velocity (these are given for 5-min intervals). The data are presented in Fig. 7.
One feature is obvious here: the CRB is located at almost 2° larger MLAT for SuperDARN at the
340 beginning of the event, and the differences are minimal toward the end of the event. Plotted in Fig.
7 the CRB location according to solely CLY velocity-scan maps is closer to that inferred from
RISR data hinting that perhaps the SuperDARN fitting procedure is the major factor for strong
differences between the SuperDARN maps and RISR measurements in this specific event. This is
not to say that RISR measurements are exact; they are very likely also subject to errors under these
345 strongly-curved flows.



350 **Figure 7:** Magnetic latitude of the flow reversal location within the dayside reverse convection cell as inferred from SuperDARN convection maps (crosses), CLY LOS velocity measurements in various beams (diamonds) and RISR measurements for the event of 04 March 2016.



355 Summary and conclusions

In this study, we attempted to validate the CLY SuperDARN radar velocity measurements by comparing them with the data collected by the Resolute Bay incoherent scatter radar. Because no line-of-sight velocity comparison is possible for the geometry of joint observations, we adopted
360 here a different approach, namely we considered eastward component of $\mathbf{E} \times \mathbf{B}$ flow vector as inferred from RISR measurements in multiple beams and compared it with either CLY velocities in a number of beams oriented eastward or with the eastward component of the plasma flow inferred from 2-D SuperDARN maps. The analysis undertaken allows us to make several conclusions.

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1. The CLY radar velocity measured in beams 4-6 is statistically comparable to the $\mathbf{E} \times \mathbf{B}$ component of the plasma drift along these beams (eastward/azimuthal plasma flows) as measured by the RISR incoherent scatter radar. This implies that the velocity data provided by the CLY radar to the SuperDARN database are reliable and suitable for convection mapping involving all
370 SuperDARN radars. The comparisons performed are an addition to the previous validation work for the RKN and INV SuperDARN radars.

2. The slope of the best linear fit line to the CLY velocity variation versus $\mathbf{E} \times \mathbf{B}$ component (as measured by RISR) applied to the binned values is on the order of 0.65 if all the available data
375 (removing data with obvious ground-scatter contamination) in the range ± 1000 m/s are considered. Correction of HF velocities on the index of refraction effect improves the slope to ~ 0.75 . The slope of the linear fit line for the corrected data is still below 1 implying that additional factors affect the relationship. Additionally, diurnal variation of the ratio of HF velocity to the RISR velocity shows strongest decrease below 1 during nighttime and not daytime.

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3. The effect of HF velocity underestimation for the CLY radar becomes progressively stronger for faster plasma drifts above ~ 750 m/s.

4. It is suggested that one of these additional factors is a bias in HF radar measurements of the
385 velocity because HF radars get stronger signals from ionospheric regions with enhanced electron



density where the electric field/ $\mathbf{E} \times \mathbf{B}$ drift can be decreased as compared to the background plasma.

5. In a case of highly-sheared plasma flows, such as near dayside reverse convection cells
390 occurring under strong IMF $B_z > 0$, the differences between RISR and SuperDARN velocity
vectors can be large.

6. Reasonable agreement between the velocities of the two systems implies that the RISR
technique of the $\mathbf{E} \times \mathbf{B}$ derivation from multiple individual radar beams is a reliable method most
395 of the time. The comparison suggests that the RISR vectors are less reliable in the midnight sector
where the flows are often very irregular, and strong vertical motions occur.

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Author contributions.

505 RG and PB worked on raw data processing and their preliminary analysis. PB prepared some diagrams. AVK did most of the comparison work and wrote the initial manuscript. All authors participated in the writing, and all commented on the paper.