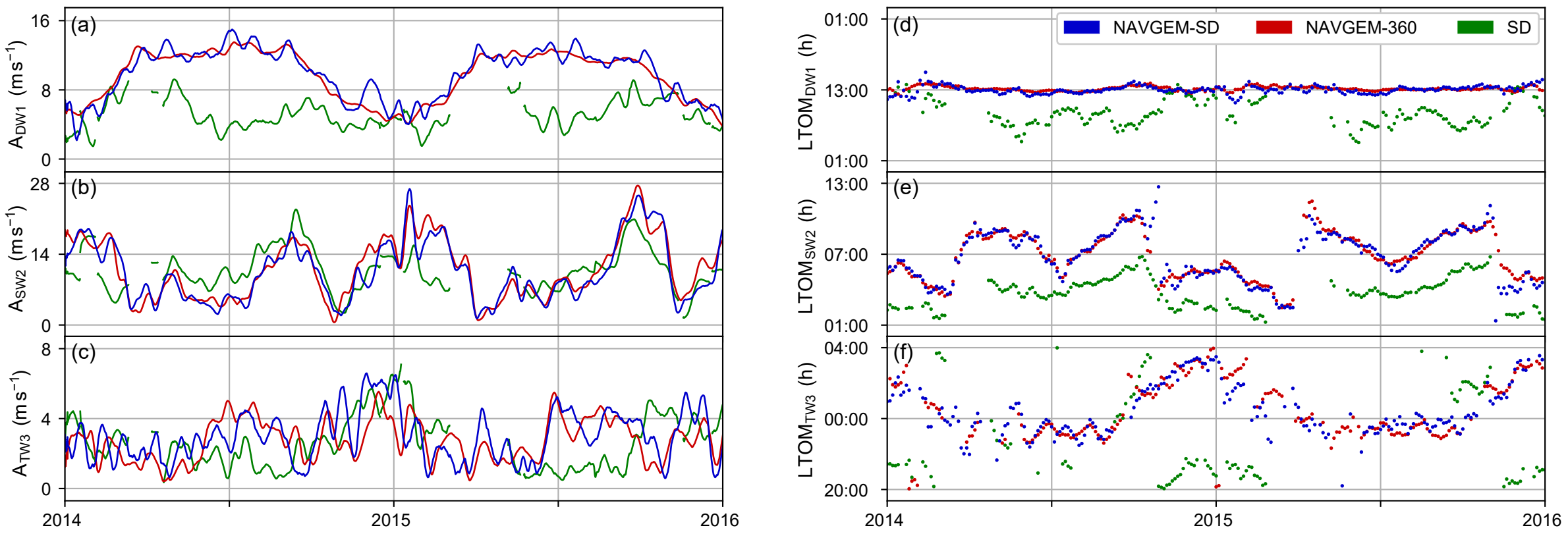
(a)
(b)
(c)
(d)
(e)
(f)
NAVGEM-SD
NAVGEM-360
SD
A_{DW1} (m s^{-1})
A_{SW2} (m s^{-1})
A_{TW3} (m s^{-1})
$LTOM_{DW1}$ (h)
$LTOM_{SW2}$ (h)
$LTOM_{TW3}$ (h)
16
8
0
28
14
0
8
4
0
01:00
13:00
01:00
13:00
07:00
01:00
04:00
00:00
20:00
2014
2015
2016
2014
2015
2016