

The first GPS-TEC imaging of the space structure of MS wave packets excited by the solar terminator

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Abstract. Using TEC measurements from the dense network of GPS sites GEONET, we have obtained the first GPS-TEC image of the space structure of medium-scale traveling wave packets (MS TWP) excited by the morning solar terminator (ST). We found that ST-generated wave packets have duration of about 1–2 h and time shift of about 1.5–6 h after the morning ST appearance at an altitude of 300 km. The TWP wave front extends along the morning ST line with the angular shift of about 20°. The time period and wave-length of ST-generated wave packets are about 10–20 min and 200–300 km, respectively. The velocity of the TWP phase front traveling is of about 300 m/s. The space image of MS TWP manifests itself in pronounced anisotropy and high coherence over a long distance of about 2000 km.

Keywords. Ionosphere (Ionospheric irregularities; Wave propagation; Instruments and techniques)

1 Introduction

A lot of investigations have shown that ST motion can generate acoustic-gravity waves (AGW), turbulence and instabilities in the ionosphere plasma (Beer, 1978; Cot and Teitelbaum, 1980; Somsikov, 1987; Somsikov and Ganguly, 1995; Hocke and Schlegel, 1996). It is worth noting that among all sources of gravity waves, the moving ST has a special status, since it is a predictable phenomenon, whose characteristics are well known. If ST is considered to be a stable and repetitive source of AGWs, one can derive information on atmospheric conditions from a response of the medium to this input.

Afraimovich (2008) has recently obtained the first GPS TEC evidence for the wave structure excited by ST mov-



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ing over the USA, Europe, and Japan. The author found two main types of the observed TEC disturbance: large-scale (LS) 60-min variations with amplitude of about 0.5-1 TECU and medium-scale (MS) 15-min variations with amplitude of about 0.05–0.1 TECU (TECU is 10^{16} m^{-2}). The first type of disturbances was predicted in theoretical investigations and registered earlier using different methods of ionosphere radio sounding. The second type of the observed TEC disturbances is traveling wave packets (TWP) generated when the time derivative of TEC is at its maximum. These TWPs have duration of about 1-2 h and time shift of about 1.5-2.5 h after the ST appearance at an altitude of 100 km. These STgenerated wave packets have been found for the first time. The relative amplitude of TEC wave packets is sufficiently low (of about 0.2%). This may be the main reason why such a phenomenon has been unknown to date.

To identify ST-generated wave packets it is insufficient to register the TEC time dependence (Afraimovich, 2008). Their spatial structure needs to be determined. But only a dense network of stations can display wave packets. We employ data from the Japanese GPS network GEONET (about 1225 stations in all). At present it is the largest regional GPS network in the world (ftp://terras.gsi.go.jp/data/ GPS_products/).

The goal of this paper is to obtain the first GEONET GPS-TEC image of the space structure of ST-generated MS TWP.

2 Methods of GPS data analyses

The data we used in this work are available in the standard RINEX format with sampling intervals of 30 s. The standard GPS technology provides means for detecting wave disturbances using phase measurements of the slant TEC I_s along the line of sight (LOS) between a GPS site and a satellite. Methods for calculating I_s using GPS phase measurements are described in detail in (Calais et al., 2003; Afraimovich

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Fig. 1. Geometry of GPS measurements during morning ST motion over Japan on 13 June 2008. Points θ and S_i mark the relative coordinate centre and the subionospheric point position for LOS between the GPS site with a number *i* and the selected satellite PRN, respectively; D_i is the distance between points θ and S_i along the great circle arc. 2-D-space distribution of the filtered TEC values dI (λ , ϕ) for PRN10 and for 22:25 UT (**a**), for 22:27 UT (**b**); for 22:29 UT (**c**); solid curves mark the morning ST line at the altitude of H=300 km on 18:25 UT (**a**), 18:27 UT (**b**), 18:29 UT (**c**), respectively. Rectangle on the panel (b) marks boundaries of region, in which velocity and direction of TWP propagation was defined. The arrows in Fig. 1c schematically show the wave vector of the TWP (green) and the normal to ST line (dark blue).

et al., 2004). We reproduce here only the final formula for phase measurements:

$$I_s(t) = \frac{1}{40.308} \frac{f_1^2 f_2^2}{(f_1^2 - f_2^2)} [(L_1 \lambda_1 - L_2 \lambda_2) + \text{const} + nL]$$
(1)

where $L_1\lambda_1$ and $L_2\lambda_2$ are additional paths of the radio signal caused by the phase delay in the ionosphere (m), L_1 and L_2 are numbers of phase rotations at the frequencies f_1 and f_2 ; λ_1 and λ_2 stand for the corresponding wavelengths, (m); "const" is the unknown initial phase ambiguity, (m); and *nL* is the error in determining the phase path (*m*). To normalize the amplitude of TEC disturbances, we use the transformation of slant TEC into the equivalent vertical value I(t) (Klobuchar, 1986):

$$I(t) = I_S(t) \times \cos\left[\arcsin\left(\frac{r_z}{r_z + h_{\max}}\cos\theta_s\right)\right]$$
(2)

where r_z is the Earth's radius; $cos\theta_s$ is the LOS elevation to the GPS satellite; h_{max} =300 or 400 km is the assumed altitude of the ionospheric F2 layer maximum. We neglect the TEC data from low LOS elevation angles (less than 45°) to reduce errors due to conversion from slant to vertical TEC.

To smooth the phase measurement noise and to select TEC variations dI(t) in the range of periods (of about 15 min) corresponding to the MS TWP one (Afraimovich, 2008), we firstly smooth the initial series with a time window of 2 min and then remove the linear trend with a window of about 20 min. The filter pass band at an amplitude level of 0.5 extends from 3 to 30 min. Here the amplitude of diurnal and large-scale TEC variations with time periods more than 1 h damp significantly (Hocke and Schlegel, 1996). A similar procedure of GPS data treatment is usually used by many authors (Calais et al., 2003; Heki and Pink, 2005; Afraimovich et al., 2004; Afraimovich, 2008, etc.).

We use two known forms of the 2-D GPS-TEC image for our presentation of the ST-generated MS TWP space structure. First we apply the diagram "distance-time" dI(t, D) used recently by different authors (Calais et al., 2003; Heki and Pink, 2005). This diagram is calculated in the polar coordinate system (Fig. 1a). Points 0 and S_i mark the relative coordinate centre and the subionospheric point position for LOS between the GPS site with a number *i* and the selected satellite PRN, respectively; D_i is the distance between points **0** and S_i along the great circle arc; α_i is the azimuth of direction D_i , counted off from the northward in a clockwise direction. Here we select the geographic latitude and longitude for points θ (48° N and 148° E) outside the GEONET GPS sites field. In this case the most probable value and root-mean-square deviation of α are 236° and 25°, respectively. Thus as a first approximation we can consider the entire set of GEONET GPS sites to be space-fixed along the most probable direction of 236° in the narrow azimuth sector of about 25° over a distance exceeding 2500 km from the relative coordinate centre $\boldsymbol{\theta}$. This location of the relative coordinate center was chosen to make more adequate correspondence between distance to each GPS site and its actual location. Also such a location of point θ provides more representative demonstration of ST effect on the ionosphere by "distance-time" diagram, because of nearer azimuth values of ST movement direction and direction at GPS site.

We determine the coordinates $x_i(t)$ and $y_i(t)$ of the subionospheric point S_i at an altitude h_{max} in the topocentric coordinate system with the center in the GPS-site as

$$x_i(t) = h_{\max} \sin(\alpha_i(t)) ctg(\theta_i(t))$$

$$y_i(t) = h_{\max} \cos(\alpha_i(t)) ctg(\theta_i(t))$$
(3)



Fig. 2. TEC wave packets on 13 June 2008, for GPS sites located along direction **D** over Japan for selected satellite number PRN10. (a) TEC series dI(t) filtered in the range of 2–20 min, for selected GPS sites 0320, 0370, 0390 and 0400, (b) the 2-D-dependence of filtered TEC series $dI(t, D_i)$ for all GPS sites S_i (total amount is 1081 sites); the horizontal lines D_{0320} and D_{0400} mark the distance *D* from the relative coordinate centre θ to GPS/GEONET sites with numbers 0320 and 0400.

 α_i is the azimuth; and θ_i is the LOS elevation (Afraimovich et al., 2004). Then we recalculate the topocentric coordinates $x_i(t)$ and $y_i(t)$ into corresponding values of the latitude ϕ and longitude λ of the subionospheric point S_i , calculate the distance D_i and then plot the 2-D-diagram "distance-time" dI(t, D) for the selected satellite number PRN. Our approximation is acceptable only for large values of θ_i . Then for the minimum θ_i value of about 45° and h_{max} =300 km, the maximum deviation of the subionospheric point S_i from GPS site does not exceed 300 km.

In order to study space properties and dynamics of TWP packets in detail we also employ another form of the 2-D-space distribution of the values of filtered TEC series dI (λ , ϕ) on the latitude ϕ and longitude λ for each 30-s TEC counts. Thus we build up the dynamic image of disturbances traveling over Japan in AVI format. The said space-time presentation method of ionosphere disturbances for dense USA GPS networks was used in Tsugawa et al. (2007).



Fig. 3. Filtered TEC series dI(t) for PRN10 and for all GPS sites S_i in dependence on the latitude ϕ and the morning terminator local time dT.

3 Results

As the first example let's consider geomagnetic quiet day on 13 June 2008 (the K_p index varied from 1.0 to 1.7, http://www.ukssdc.ac.uk/wdcc1/wdc_menu.html). Figure 2b presents the 2-D-dependence of TEC series $dI(t, D_i)$, filtered in the range of 2–20 min, for all GEONET sites S_i (total amount is 1081 sites) and the satellite PRN10. The amplitude of dI is of about 0.1 TECU (scale for dI is plotted on panel **b** at the right). TEC series $dI(t)_i$ for the selected GPS/GEONET sites 0320, 0370, 0390 and 0400 are shown on panel (a). On panel (b), the horizontal lines \mathbf{D}_{0320} and \mathbf{D}_{0400} mark the distances **D** from the relative coordinate centre θ to GPS/GEONET sites with numbers 0320 and 0400. One can see that TWP travels for \mathbf{D}_{0320} - \mathbf{D}_{0400} distance without a change of shape, but with the time shift (the moment of t_{\min} is marked by thick dots on panel a). Hence TWP travels at apparent propagation velocity $V = \sim 370 \text{ m/s}$ southwest from the point O over D=1800 km. The velocity V is defined through the inclination of the line that approximates the dependence of t_{\min} on the distance **D** (the black line on panel b).

The hypothesis on the connection between the TWP generation and the solar terminator (Afraimovich, 2008) can be tested in the terminator local time (TLT) system: $dT=T_{OBS}-T_{ST}$, where T_{OBS} is the observation time at the given point; T_{ST} is the arrival time of ST at the altitude of H over this point. In other words, we first transform the latitude and longitude of this point to an arrival time of ST T_{ST} over this point and then we define the difference dT between the observation time at the given point and the arrival time of ST over this point. A distinctive feature of this approach is

in excluding certain coordinates of measurement points and considering data on each point in the solar terminator local time only. Figure 3 presents the 2-D-dependence of TEC series $dI (dT, \phi)$ for all GEONET sites S_i (total amount is 1081 sites) at TLT dT for H=300 km and geographic latitude ϕ for the selected satellite number PRN10. This dependence has been obtained through the transformation of the time t(UT) into TLT dT (h) from the initial TEC series dI(t, D)(Fig. 2b). The TWP 2-D-structure is observed to comprise strong anisotropic waves with the transverse wave-length of about 250 km and the longitudinal dimension of the phase front exceeding 1500 km. The time delay dT of TWP appearance varies from 2.5 h at 30° N to 6 h at 45° N.

It should be noted that the apparent propagation velocity defined by the diagram "distance-time" dI(t,D) corresponds to the velocity projection at the line of primary GPS site distribution (the mean value is 236°, see Sect. 2). To determine proper values of the propagation velocity V and direction ψ of the TWP wave front travel, it is necessary to make 2-D picture of TEC disturbance.

Figure 1 presents 2-D-space distributions of the filtered TEC values $dI(\lambda, \phi)$ for 22:25 UT (a), for 22:27 UT (b); for 22:29 UT (c), respectively. Data of each GPS site is represented in the points with coordinates of subionosphere points for LOS between this site and PRN10. Solid curves mark the ST line at the altitude of H=300 km for 18:25 UT (a), 18:27 UT (b), 18:29 UT (c), respectively. The preliminary analysis showed that the MS TWP space image manifests itself in pronounced anisotropy and high coherence over a long distance of about 2000 km. The TWP wave front travels predominantly south-westward.

The dynamic image analysis of dI (λ , ϕ , t) with a time interval of 30 s gives a precise estimation of the propagation velocity V and azimuth ψ of normal line to the TWP wave front. We employ a method of determining above parameters (SADM-GPS) taking into account the relative motion of subionosphere points (Afraimovich et al., 2004). Various combinations of 3-sites GPS arrays in the region of 32°-38° N, 132°–140° E (green rectangle in Fig. 1b) for the time interval of 22:00-22:50 UT totaled 191. We select GPS arrays with the base line from 50 km to 60 km. As deduced from our data, the TWP horizontal propagation velocity Vvaries from 250 to 450 m/s, with the most probable value of 350 m/s. The analysis of the distribution of the TWP traveling azimuth ψ shows a clearly pronounced south-westward direction of TWP displacement of 250° (r.m.s. is 15°). Since the precise azimuth value is close to the preferred direction azimuth of GPS/GEONET location, the precise velocity value is close to V=370 m/s found from the "distancetime" diagram. The mean value of the oscillation time period (\sim 16 min) corresponds to that of the TWP wave-length of about 300 km.

The arrows in Fig. 1c schematically show the wave vector of the TWP (green) and the normal to the morning ST line (dark blue). It is seen that the TWP wave front extends along the ST line with the angular shift of about 20°. This agrees with the 2-D-distribution of TEC series $dI (dT, \phi)$, Fig. 3. However, the TWP velocity V exceeds that of the ST-line traveling (256 m/s).

4 Conclusion

We have thus obtained the first GEONET GPS-TEC image of the space structure of MS wave packets excited by the solar terminator and lent support to the validity of the discovery of ST wave packets made by Afraimovich (2008). Our observations also confirm that the ST is a stable and repetitive source of ionospheric wave disturbances (Somsikov, 1987). We found that ST-generated wave packets have duration of about 1-2 h and time shift of about 1.5-6 h after the morning ST appearance at an altitude of 300 km. The TWP wave front extends along the ST line with the angular shift of about 20° . The time period and wave-length of ST-generated wave packets are about 10-20 min and 100-300 km, respectively. The velocity of the TWP phase front traveling is of about 300 m/s. The space image of MS TWP manifests itself in pronounced anisotropy and high coherence over a long distance of about 2000 km.

The obtained results do not completely agree with the known mechanisms of the ionosphere irregularity generation and propagation (Somsikov, 1987; Somsikov and Ganguly, 1995) and can stimulate the development of the theory. The question on the source of the observed TEC oscillation is still unclear. It is known that TIDs can propagate without significant attenuation and changes in their shape or loss of their coherence no farther than 3–5 wave-lengths; MS TIDs can propagate no farther than 1000 km (Francis, 1974). The second problem is the time delay of wave packet appearance after the ST passage. The delay may be determined by the correlation between the time damping of MS AGW and the dynamics of TEC growing under different geophysical conditions.

Our results are important for ionospheric irregularity physics development and the transionosphere radio wave propagation modeling. Spatial-temporal features and modeling of MS TWP are the aims of our future investigations.

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